



COMPETITIVE PHYSICS INFORMED NETWORKS

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Various real-world applications are usually described by partial differential equations (PDEs).

- Navier-Stokes Eq.
- Schrödinger Eq.
- Maxwell Eq.
- numerical algorithms
 - computationally expensive
 - face severe challenges in multi-physics and multi-scale systems
 - data assimilation introduces additional uncertainties
- machine learning
 - Physics-informed Neural Networks (PINNs): encode PDEs into the loss function of neural networks

$$\begin{aligned}\mathcal{A}[u] &= f, & \text{in } \Omega \\ u &= g, & \text{on } \partial\Omega,\end{aligned}$$

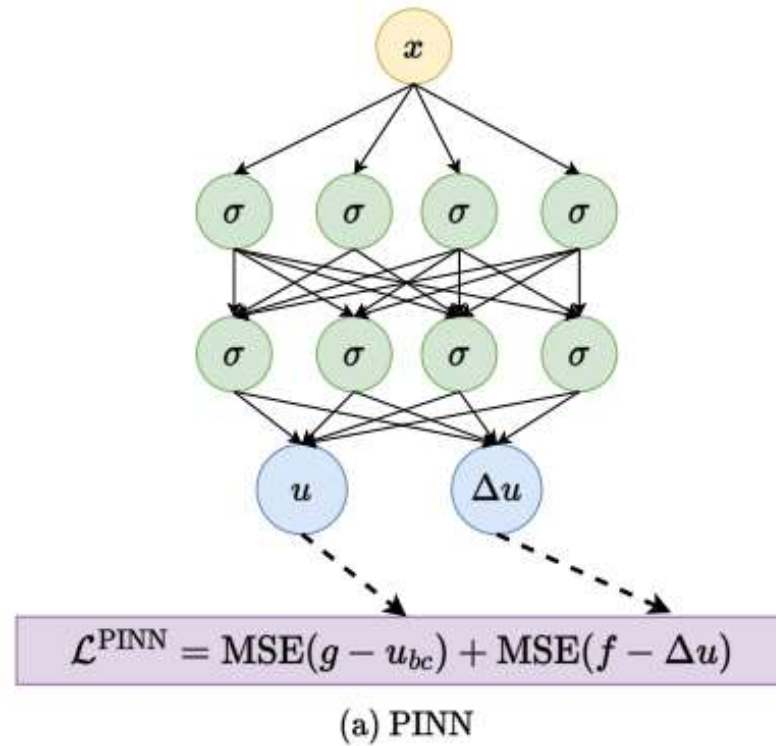


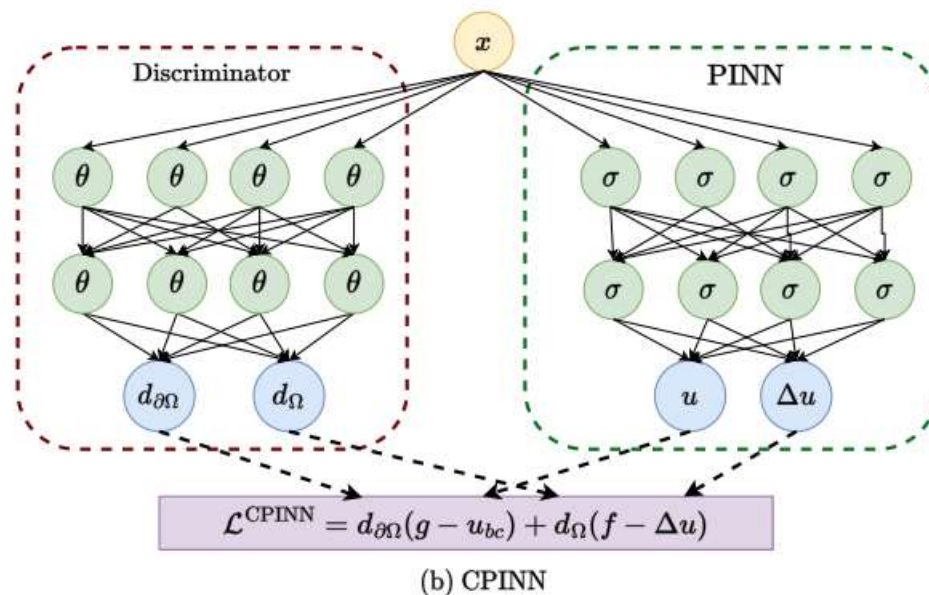
use neural network to approximate u

$$\mathcal{L}^{\text{PINN}}(\mathcal{P}, \mathbf{x}, \bar{\mathbf{x}}) = \mathcal{L}_{\Omega}^{\text{PINN}}(\mathcal{P}, \mathbf{x}_{\Omega}) + \mathcal{L}_{\partial\Omega}^{\text{PINN}}(\mathcal{P}, \bar{\mathbf{x}}),$$

$$\mathcal{L}_{\Omega}^{\text{PINN}}(\mathcal{P}, \mathbf{x}) = \frac{1}{N_{\Omega}} \sum_{i=1}^{N_{\Omega}} (\mathcal{A}[\mathcal{P}](x_i) - f(x_i))^2$$

$$\mathcal{L}_{\partial\Omega}^{\text{PINN}}(\mathcal{P}, \bar{\mathbf{x}}) = \frac{1}{N_{\partial\Omega}} \sum_{i=1}^{N_{\partial\Omega}} (\mathcal{P}(\bar{x}_i) - g(\bar{x}_i))^2$$





$$\max_{\mathcal{D}} \min_{\mathcal{P}} \mathcal{L}_{\Omega}^{\text{CPINN}}(\mathcal{P}, \mathcal{D}, \mathbf{x}) + \mathcal{L}_{\partial\Omega}^{\text{CPINN}}(\mathcal{P}, \mathcal{D}, \bar{\mathbf{x}}),$$

$$\mathcal{L}_{\Omega}^{\text{CPINN}}(\mathcal{D}, \mathcal{P}, \mathbf{x}) = \frac{1}{N_{\Omega}} \sum_{i=1}^{N_{\Omega}} \mathcal{D}_{\Omega}(x_i) (\mathcal{A}[\mathcal{P}](x_i) - f(x_i)) \quad \mathcal{L}_{\partial\Omega}^{\text{CPINN}}(\mathcal{D}, \mathcal{P}, \bar{\mathbf{x}}) = \frac{1}{N_{\partial\Omega}} \sum_{i=1}^{N_{\partial\Omega}} \mathcal{D}_{\partial\Omega}(\bar{x}_i) (\mathcal{P}(\bar{x}_i) - g(\bar{x}_i))$$

The Nash equilibrium of this game is: $\mathcal{P} \equiv u$ and $\mathcal{D} \equiv 0$

$$\mathcal{P}(x) = \sum_{i=1}^{\dim(\pi)} \pi_i \psi_i(x), \quad \mathcal{D}(x) = \sum_{i=1}^{\dim(\delta)} \delta_i \phi_i(x),$$

$$A \in \mathbb{R}^{N_\Omega \times \dim(\pi)}$$

$$f \in \mathbb{R}^{N_\Omega}$$



$$A_{ij} := \mathcal{A}[\psi_j](x_i), \quad f_i := f(x_i)$$

$$A\pi = f$$

For PINNs: $\min_{\pi} \|A\pi - f\|^2$

$$\pi = (A^\top A)^{-1} A^\top f \quad \kappa(A^\top A) = \kappa(A)^2$$

For CPINNs: $\min_{\pi} \max_{\delta} \delta^\top (A\pi - f)$

$$\begin{bmatrix} 0 & A^\top \\ A & 0 \end{bmatrix} \begin{bmatrix} \pi \\ \delta \end{bmatrix} = \begin{bmatrix} 0 \\ f \end{bmatrix}, \quad \text{with} \quad \kappa \left(\begin{bmatrix} 0 & A^\top \\ A & 0 \end{bmatrix} \right) = \kappa(A)$$

POISSON EQUATION, NONLINEAR SCHRÖDINGER EQUATION,
BURGERS' EQUATION, ALLEN–CAHN EQUATION

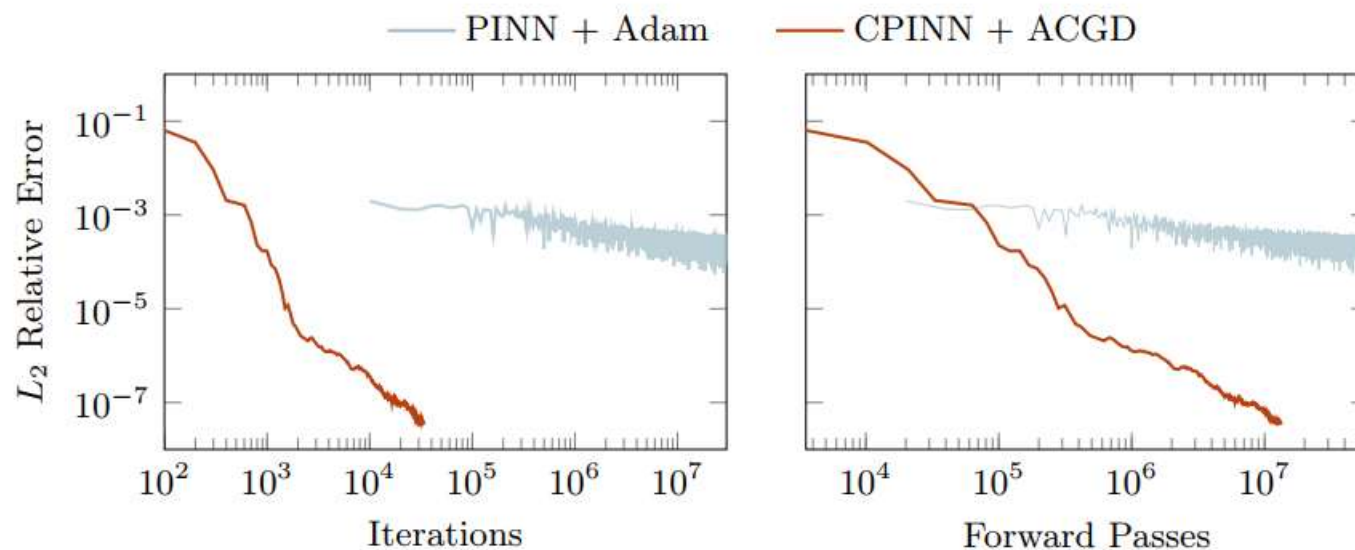


Figure 1: Comparison of CPINN and PINN on the Poisson problem of equation 15 in terms of relative error. CPINN has a faster convergence rate and reduces the L_2 error to 1.7×10^{-8} , whereas the PINN case has an L_2 error of 1.2×10^{-4} even with a larger computational budget.

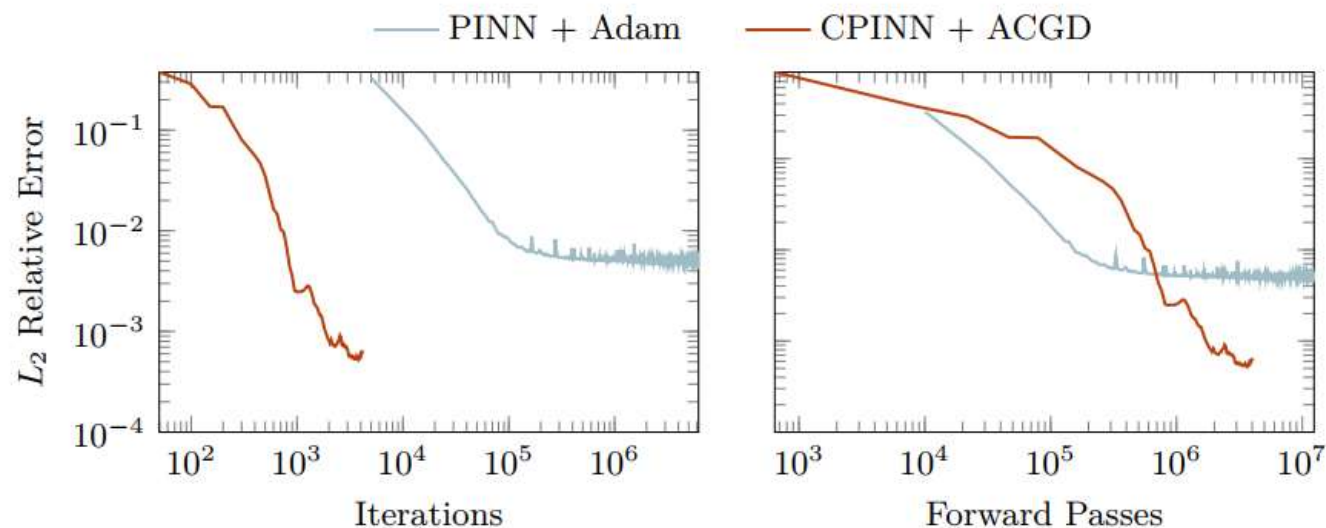


Figure 3: Comparison of CPINN and PINN on the nonlinear Schrödinger eq. (21) in terms of relative errors. After 200 000 training iterations, PINN cannot reduce the L_2 error further, plateauing about 4×10^{-3} , whereas CPINN reduces the error to 6×10^{-4} under a smaller computational budget.

Table 1: Performance of CPINNs and PINNs on the 2D Poisson problem of equation 15.

	Optimizer	Iterations	L_2 Rel. Error	$\mathcal{L}^{\text{PINN}}$	$\mathcal{L}_{\Omega}^{\text{PINN}}$	$\mathcal{L}_{\partial\Omega}^{\text{PINN}}$
PINN	Adam	3×10^7	1.2×10^{-4}	1.4×10^{-8}	8.4×10^{-8}	5.5×10^{-9}
	SGD	2.2×10^7	1.3×10^{-3}	1.1×10^{-6}	5.2×10^{-7}	6.3×10^{-7}
CPINN	ACGD	4.8×10^4	1.7×10^{-8}	2.1×10^{-14}	2×10^{-14}	6×10^{-16}
	CGD	6×10^5	3.5×10^{-4}	5.1×10^{-7}	3.5×10^{-7}	1.7×10^{-7}
	XAdam	8.5×10^6	1.6	1.6×10^6	1.6×10^6	0.2
	XSGD	8.5×10^6	1.2×10^{-4}	1.2×10^{-7}	9.2×10^{-8}	3×10^{-8}
WAN	Adam + Adagrad	1.3×10^6	1.2	2.6	2.6	1.2×10^{-3}
	ACGD	1.8×10^5	9×10^{-3}	1.1×10^{-3}	1.1×10^{-3}	2.7×10^{-5}