

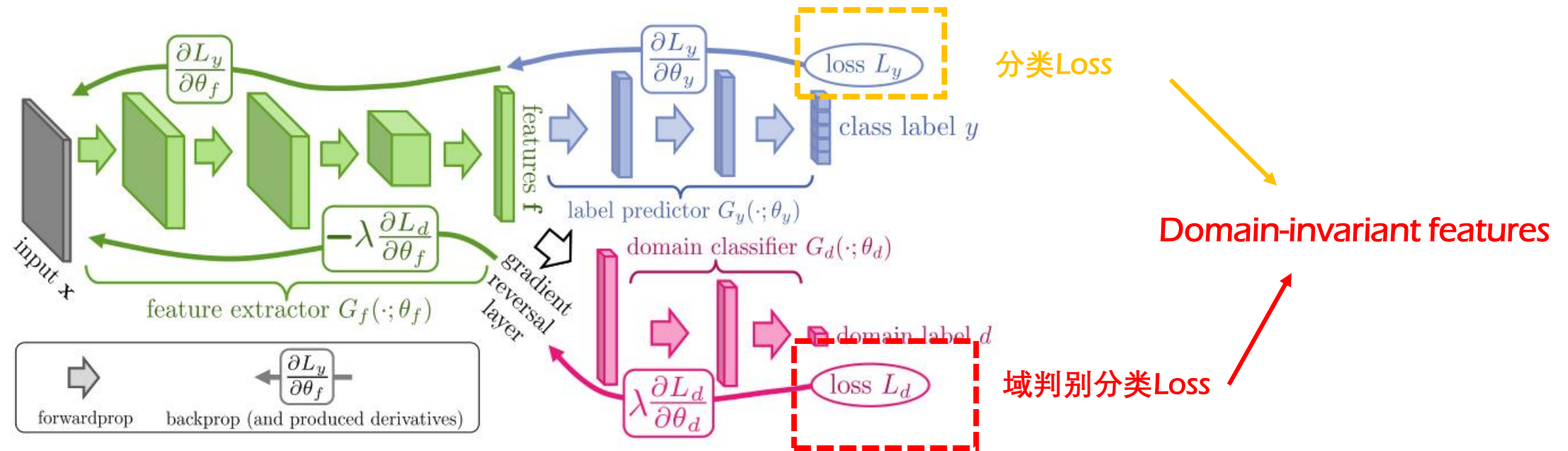


Asymmetric Tri-training for Unsupervised Domain Adaptation

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Background — Domain-Adversarial Training of Neural Networks

- DANN aimed at obtaining **domain-invariant features** by minimizing the divergence between domains, as well as a category loss on the source domain.



Domain-Adversarial Training of Neural Networks_[1]

$$\epsilon_T(h) \leq \epsilon_S(h) + \frac{1}{2} d_{\mathcal{H}\Delta\mathcal{H}}(\mathcal{D}_S, \mathcal{D}_T) + \lambda$$

$$h^* = \operatorname{argmin}_{h \in \mathcal{H}} \epsilon_S(h) + \epsilon_T(h)$$

$$\lambda = \epsilon_S(h^*) + \epsilon_T(h^*)$$

Motivation

- DANN aims to learn **domain-invariantly discriminative representations**.
- However, if a classifier that works well on both the source and the target domains does not exist, we theoretically cannot expect a discriminative classifier to be applicable to the target domain.
- This methods aims to learn **target-discriminative representations for target domain** by assigning pseudo-label to the target samples and training the target-specific networks as if they were true labels.

Two View

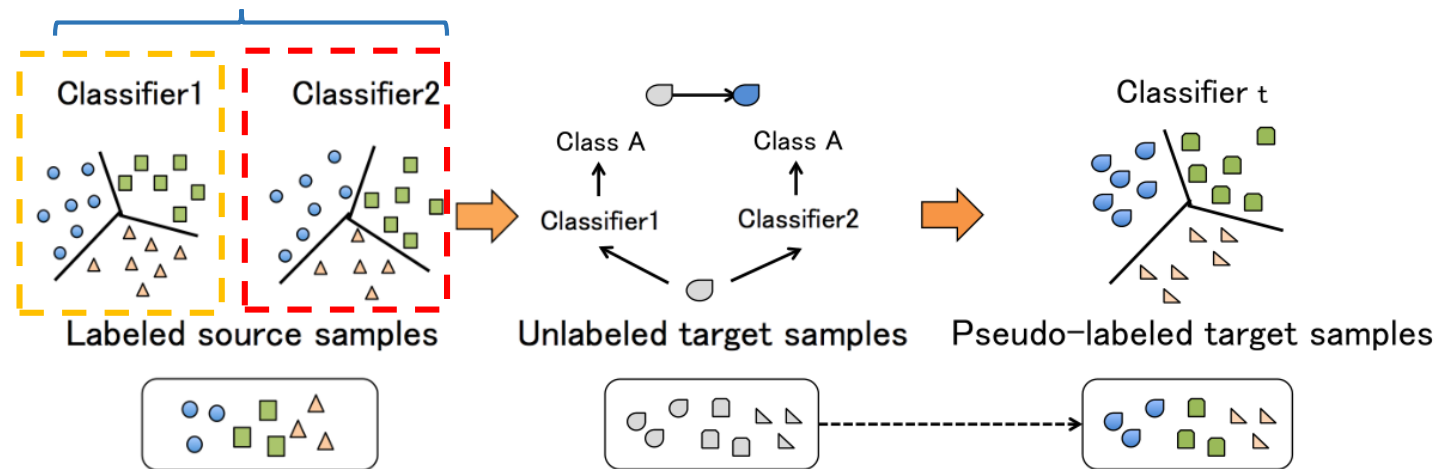
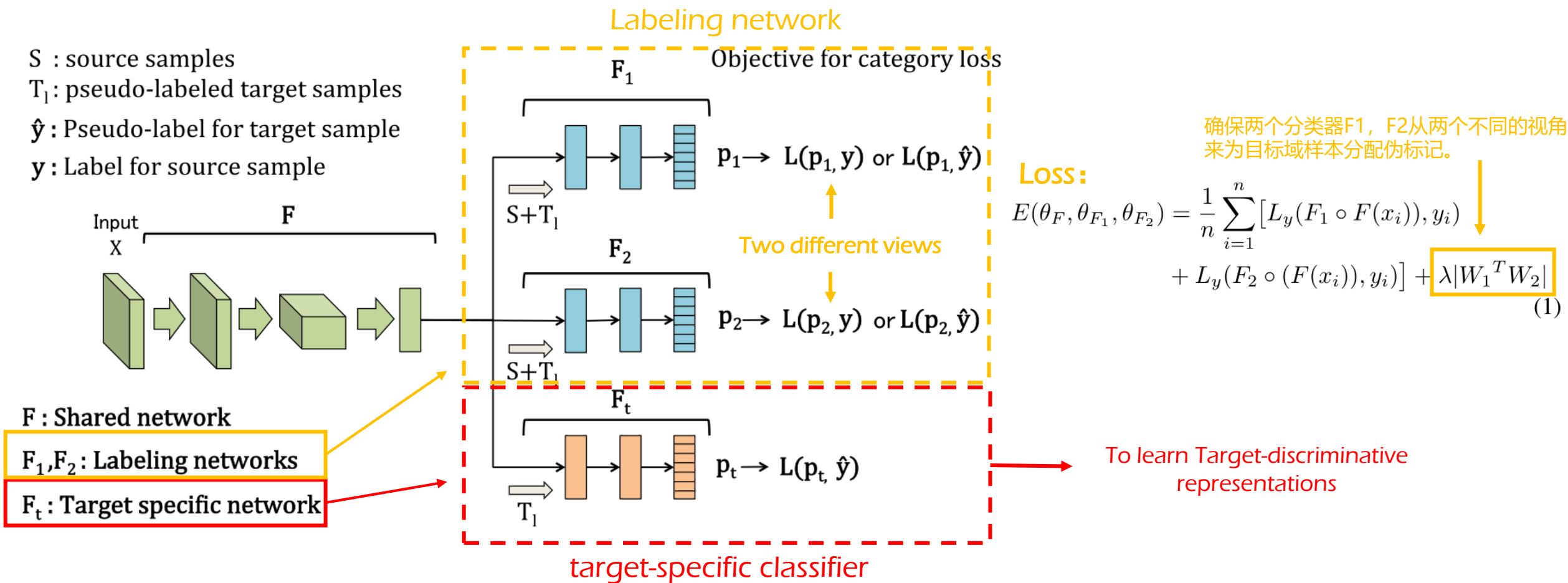


Figure 1. Outline of our model. We assign pseudo-labels to unlabeled target samples based on the predictions from two classifiers trained on the source samples.

Method — Asymmetric Tri-training

➤ Asymmetric means that every classifiers has been assigned different roles.



Algorithm 1 *iter* denotes the iteration of the training. The function *Labeling* indicates the labeling method. We assign pseudo-labels to samples when the predictions of F_1 and F_2 agree, and at least one of them is confident of their predictions.

Input: data

$$\mathbf{X}^s = \{(x_i, t_i)\}_{i=1}^m, \mathbf{X}^t = \{(x_j)\}_{j=1}^n$$

$$\mathbf{X}^{t_l} = \emptyset$$

for $j = 1$ **to** *iter* **do**

Train F, F_1, F_2, F_t with a mini-batch from the training set \mathcal{S}

end for

$$N_t = N_{init} \text{ \# 5000}$$

$$\mathbf{X}^{t_l} = \text{Labeling}(F, F_1, F_2, \mathbf{X}^t, N_t)$$

$$\mathcal{L} = \mathbf{X}^s \cup \mathbf{X}^{t_l}$$

for K steps **do**

for $j = 1$ **to** *iter* **do**

Train F, F_1, F_2 with mini-batch from training set \mathcal{L}

Train F, F_t with mini-batch from training set \mathbf{X}^{t_l}

end for

$$\mathbf{X}^{t_l} = \emptyset, N_t = K/20 * n$$

$$\mathbf{X}^{t_l} = \text{Labeling}(F, F_1, F_2, \mathbf{X}^t, N_t)$$

$$\mathcal{L} = \mathbf{X}^s \cup \mathbf{X}^{t_l}$$

end for

Labeling() 为目标域数据加入伪标记

Two conditions:

1. 两个分类器给出相同的分类标记（两个视图）.
2. 分类置信度 > 0.9 or 0.95

N_t : pseudo-labeled candidates

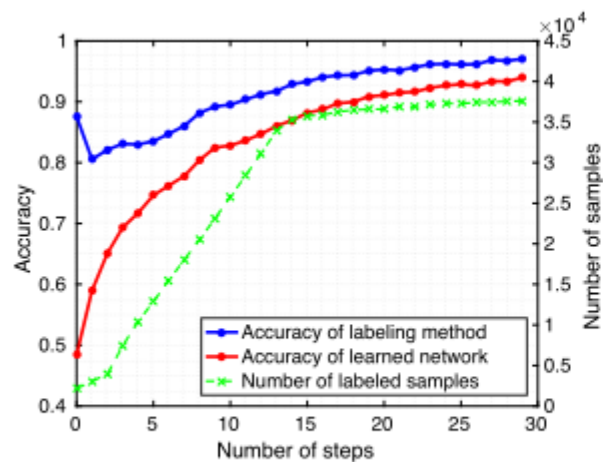
METHOD	SOURCE	MNIST	SVHN	MNIST	SYN DIGITS	SYN SIGNS
	TARGET	MNIST-M	MNIST	SVHN	SVHN	GTSRB
Source Only w/o BN		59.1(56.6)	68.1(59.2)	37.2(30.5)	84.1(86.7)	79.2(79.0)
Source Only with BN		57.1	70.1	34.9	85.5	75.7
MMD (Long et al., 2015b)		76.9	71.1	-	88.0	91.1
DANN (Ganin & Lempitsky, 2014)		81.5	71.1	35.7	90.3	88.7
DRCN (Ghifary et al., 2016)		-	82.0	40.1	-	-
DSN (Bousmalis et al., 2016)		83.2	82.7	-	91.2	93.1
kNN-Ad (Sener et al., 2016)		86.7	78.8	40.3	-	-
Ours w/o BN		85.3	79.8	39.8	93.1	96.2
Ours w/o weight constraint ($\lambda = 0$)		94.2	86.0	49.7	92.4	94.0
Ours		94.0	85.8	52.8	92.9	96.2

Table 1. Results of the visual domain adaptation experiment on digit and traffic sign datasets. In every setting, our method outperforms other methods by a large margin. In the source-only results, we show the results reported in (Bousmalis et al., 2016) and (Ghifary et al., 2016) in parentheses.

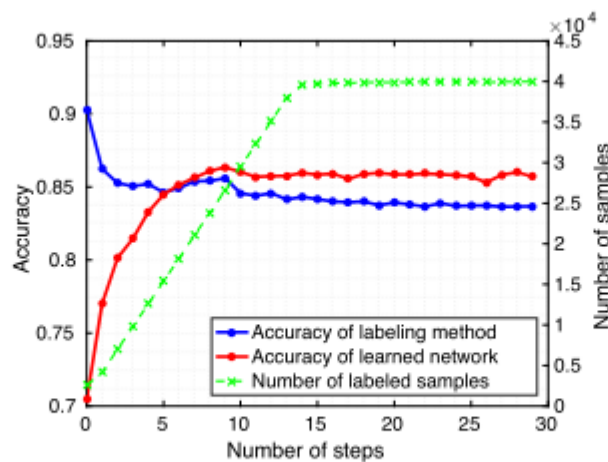
Source→Target	VFAE	DANN	Our method
books→dvd	79.9	78.4	80.7
books→electronics	79.2	73.3	79.8
books→kitchen	81.6	77.9	82.5
dvd→books	75.5	72.3	73.2
dvd→electronics	78.6	75.4	77.0
dvd→kitchen	82.2	78.3	82.5
electronics→books	72.7	71.1	73.2
electronics→dvd	76.5	73.8	72.9
electronics→kitchen	85.0	85.4	86.9
kitchen→books	72.0	70.9	72.5
kitchen→dvd	73.3	74.0	74.9
kitchen→electronics	83.8	84.3	84.6

Table 3. Amazon Reviews experimental results. The accuracy (%) of the proposed method is shown with the result of VFAE (Louizos et al., 2015) and DANN (Ganin et al., 2016).

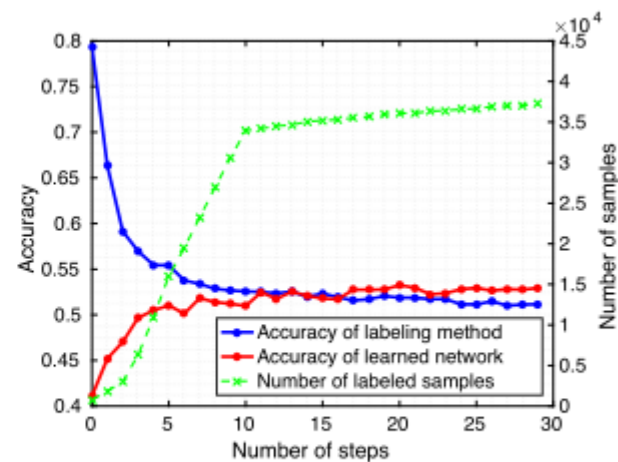
Experiments



(a) MNIST→MNIST-M

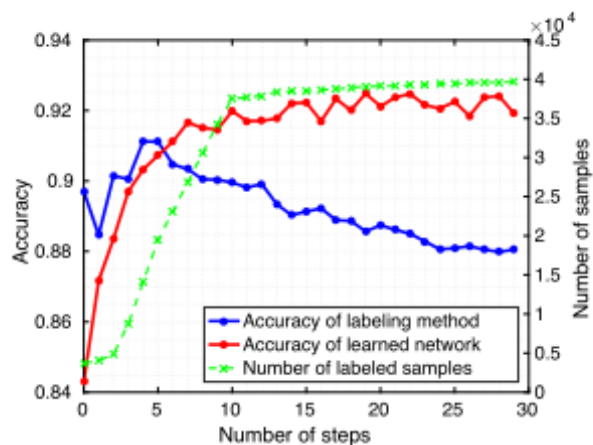


(b) SVHN→MNIST

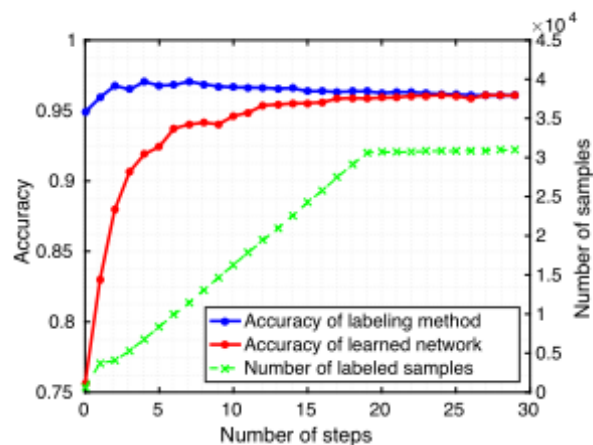


(c) MNIST→SVHN

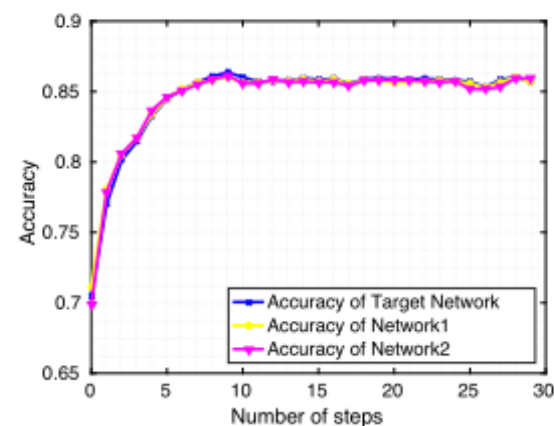
Labeling accuracy : (the number of correctly labeled samples)/(the number of labeled samples)



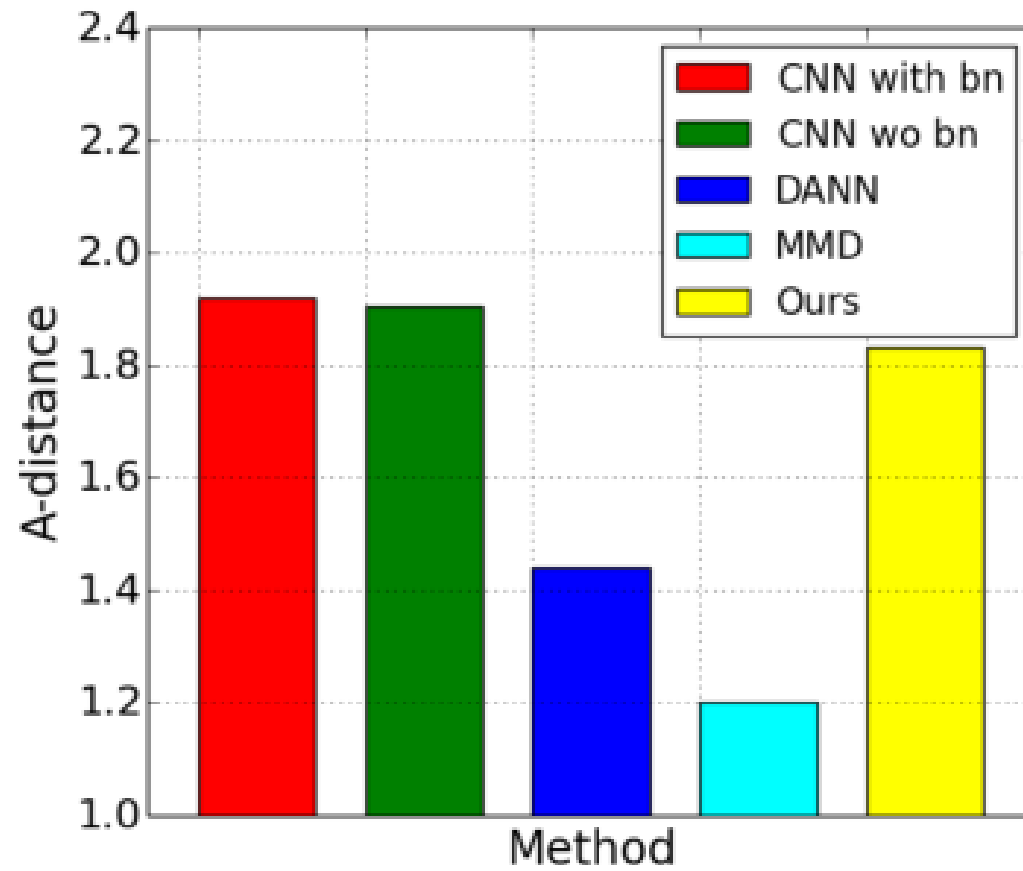
(d) SYNDIGITS→SVHN



(e) SYNSIGNS→GTSRB



(f) Comparison of accuracy of three networks on SVHN→MNIST



$$\hat{d}_{\mathcal{A}} = 2(1 - 2\epsilon)$$

ϵ is a generalization error

(g) \mathcal{A} -distance in MNIST \rightarrow MNIST-M

Thanks