



A Cost-sensitive Active Learning for Imbalance Data with Uncertainty and Diversity Combination

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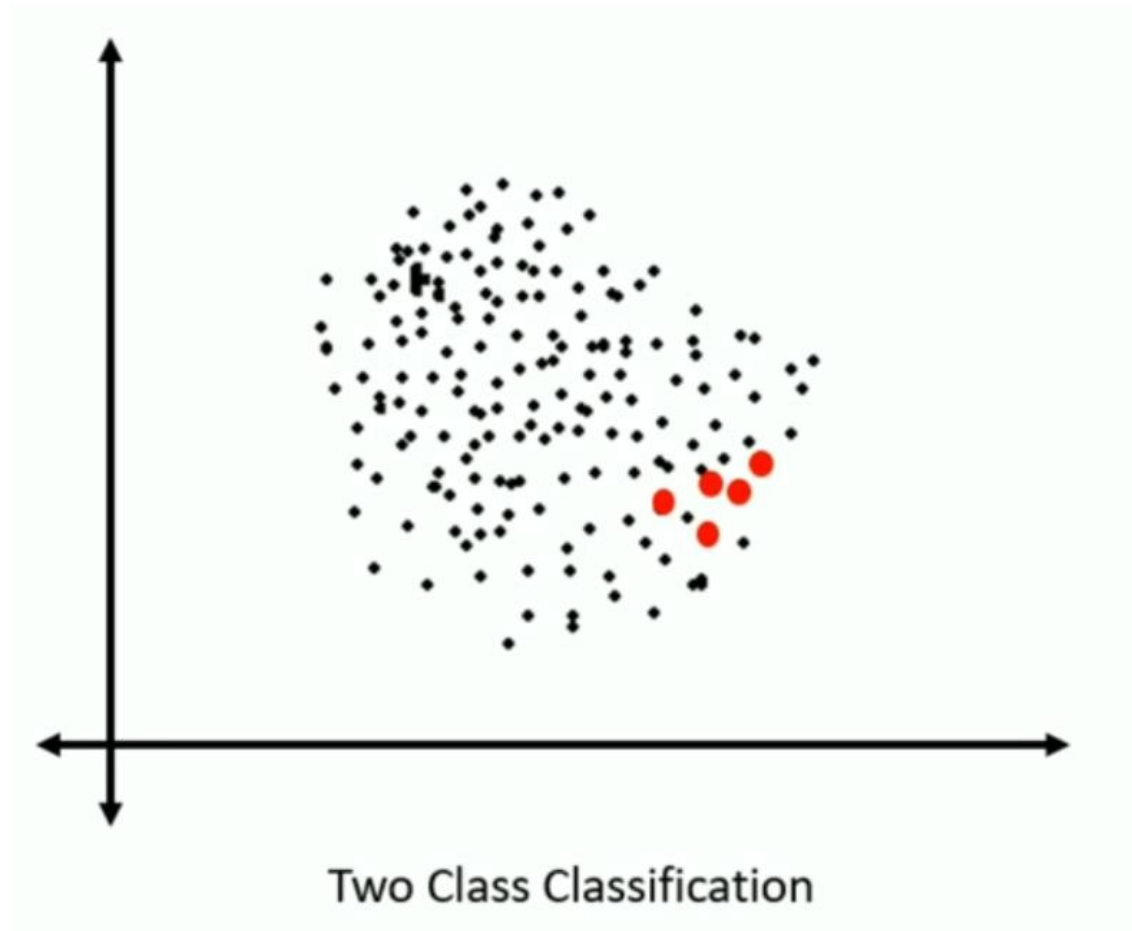
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Introduction

The class distributions of real-world classification datasets are usually imbalanced because many applications, such as network intrusion detection, tumor classification, financial risk identification, etc.



Two difficulties that we may face are:

imbalanced class distributions



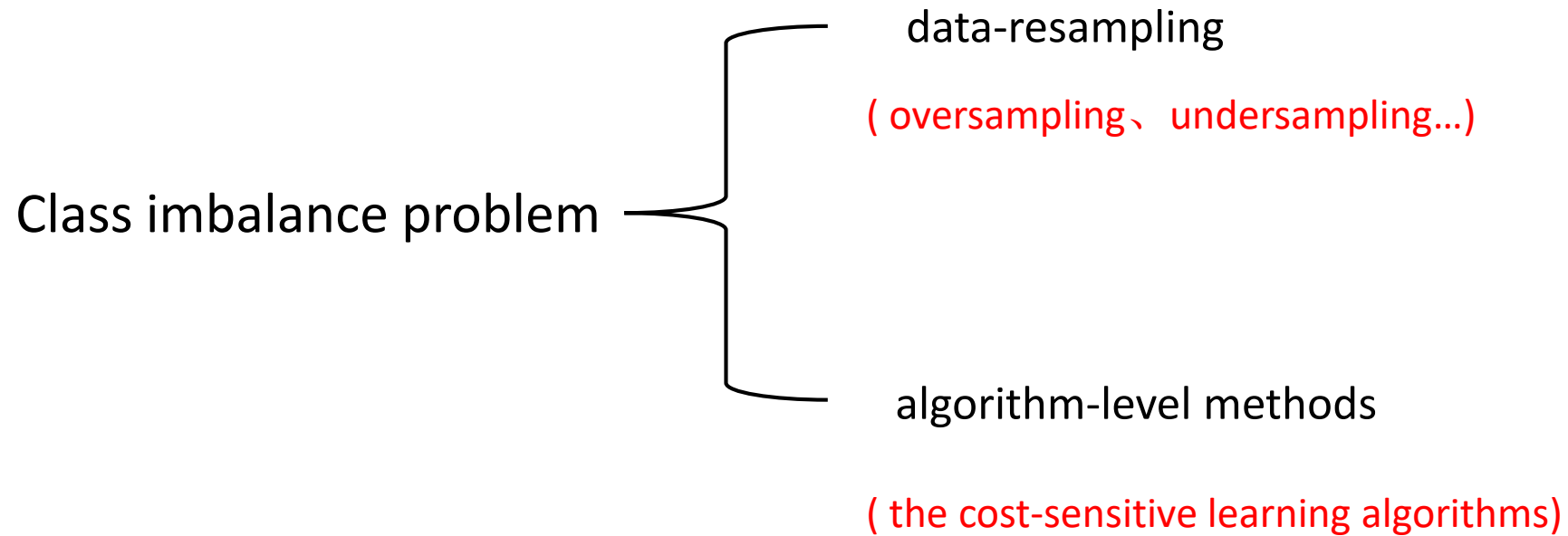
Imbalanced learning

selecting proper training samples



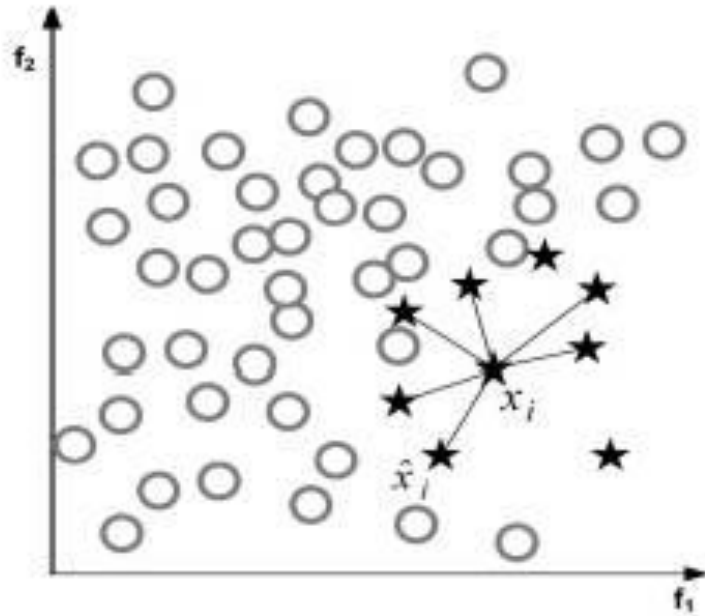
active learning

Introduction

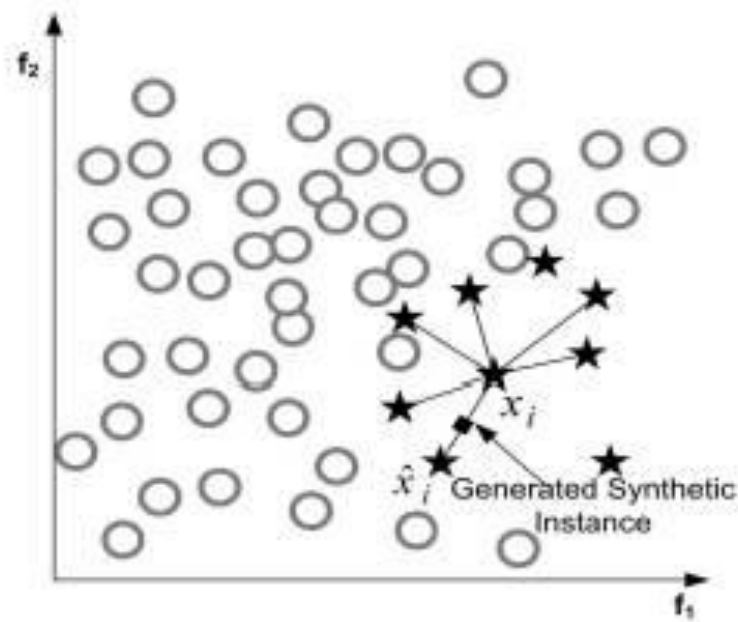


SMOTE算法

(Synthetic Minority Oversampling Technique)



(a)



(b)

★ randomly select a minority point and find its kNN point in the minority. Then randomly mark a point from kNN.

★ Randomly select a point on the line between a and b as the newly synthesized minority sample

Introduction

Contributions:

A novel cost-sensitive active learning framework that combines uncertainty and diversity measures for sample selection is proposed for imbalanced learning.

A novel algorithm that measures the diversity of examples is proposed, where the K-means clustering is firstly used to scatter examples.

A set of experiments are conducted on several class-imbalanced datasets to confirm the advantages of the proposed method over some state-of-the-art methods.

Method

1、Uncertainty Measure

the labeled dataset is $\mathcal{L} = \{x_1, x_2, \dots, x_n\}$

the unlabeled dataset is $\mathcal{U} = \{x_{n+1}, x_{n+2}, \dots, x_{n+m}\}$

$$y_i = \begin{cases} -1, & \mathcal{F}(x_i) < \theta \\ 1, & \mathcal{F}(x_i) \geq \theta \end{cases} \qquad \text{unc}_i = |\mathcal{F}(x_i) - \theta|$$

(the model function)

Smaller distance means that the prediction result on is more uncertain.

Method

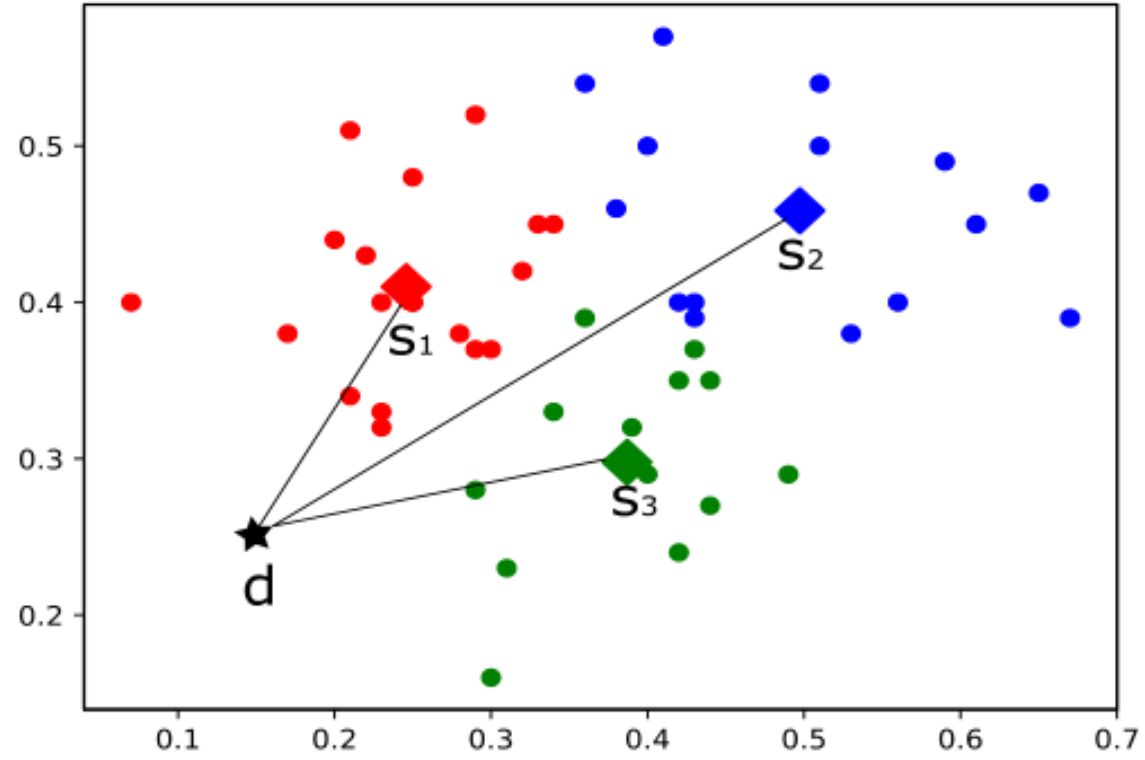
2、 Diversity Measure

(1) $\mathcal{D} = \{d_1, d_2, \dots, d_t\} \subseteq \mathcal{U}$

$\mathcal{L} = \{l_1, l_2, \dots, l_l\} \xrightarrow{\text{k-means}} \text{k center points } (C_j)$

(2) $D_d = \sum_{j=1}^k \|c_j - d\|^2$

(3) choose samples in whose distance is far from all center points to make our selected samples diverse.



The distance D_d is the sum of the distance of s_1d , s_2d , and s_3d .

Algorithm Imbalanced Active Learning (IAL)

Input: labeled dataset $\mathcal{L}$, Unlabeled data pool $\mathcal{U}$, parameters m_s and m_l

Output: Classifier $\mathcal{F}$

1. Initialize k of k-means cluster algorithm, t, n

2. REPEAT // In each iteration j

2.1 Calculate the class weight $\omega_v = \frac{m_l}{m}$ and $\omega_\mu = \frac{m_s}{m}$.

Classifier $\mathcal{F}_j \leftarrow \text{Train}(\omega_v, \omega_\mu, \mathcal{L})$

Obtain the center points $\{c_i\}$ of $\mathcal{L}$ using k-means cluster algorithm

2.2 Calculate the uncertainty of instances by Eq. (2)

Get the most t uncertain samples ($\mathcal{D}$)

FOR d in $\mathcal{D}$ **DO**

Calculate the diversity of instances by Eq. (3)

Get the most n diverse samples in $\mathcal{D}$.

2.3 Query the labels of the n samples, add the labeled n samples to the labeled dataset $\mathcal{L}$, update $\mathcal{U}$.

UNTIL the performance of $\mathcal{F}$ is satisfied.

3. RETURN $\mathcal{F}$

$$\underline{unc_i = |\mathcal{F}(x_i) - \theta|}$$

$$\underline{D_d = \sum_{j=1}^k \|c_j - d\|^2}$$

Experiments: Dataset

Table 1. Characteristics of the six datasets

dataset	size	#attribs	#major/#minor	ratio
<i>Yeast1</i>	1484	8	1055/429	2.46
<i>Vehicle2</i>	846	18	628/218	2.88
<i>Ecoli1</i>	336	7	259/77	3.36
<i>Segment0</i>	2308	19	1979/329	6.02
<i>Page-block0</i>	5472	10	4913/559	8.79
<i>Abalone9-18</i>	731	8	689/42	16.4

Experiments: Evaluation Metrics

Table 2. Confusion matrix

	Predict Positive	Predict Negative
True Positive	TP	FN
True Negative	FP	TN

Specificity:

$$Specificity = \frac{TN}{TN+FP} \quad (4)$$

Precision:

$$Precision = \frac{TP}{TP+FP} \quad (5)$$

Recall:

$$Recall = \frac{TP}{TP+FN} \quad (6)$$

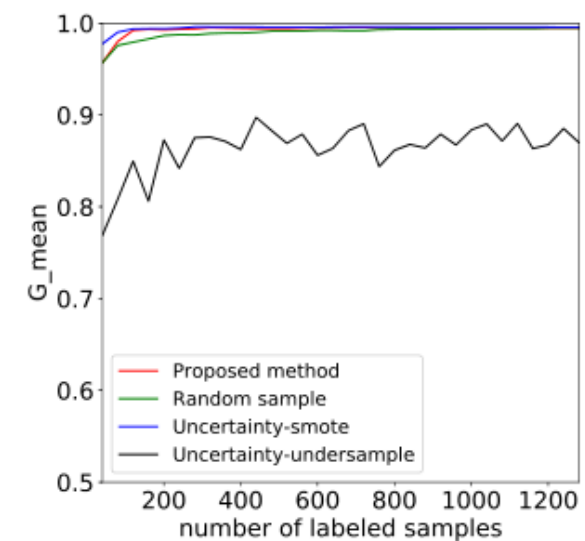
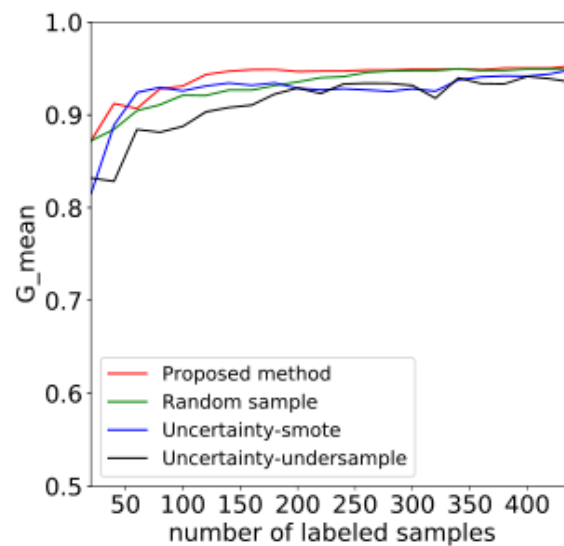
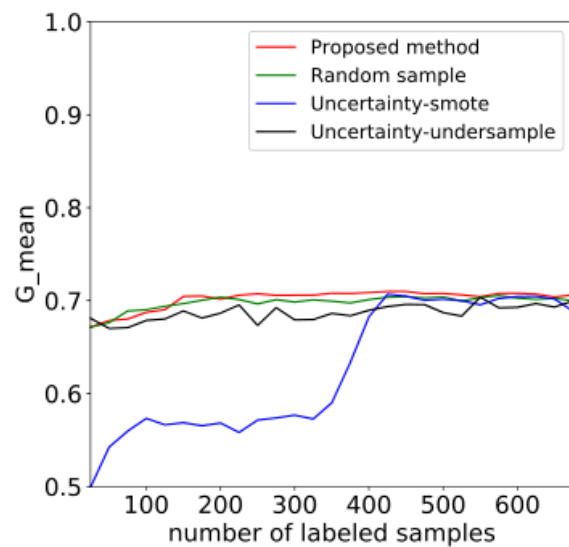
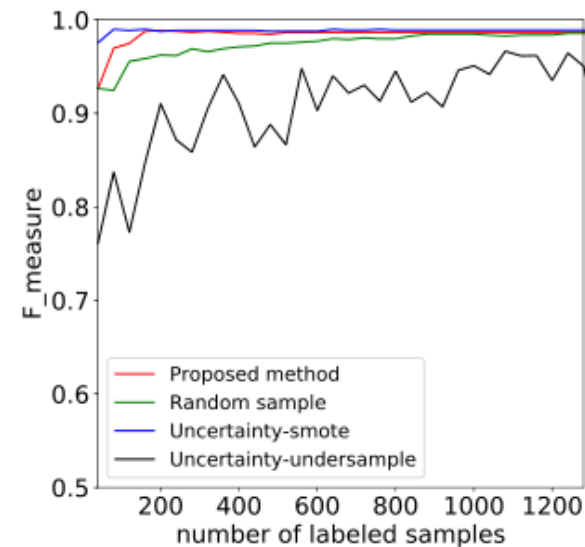
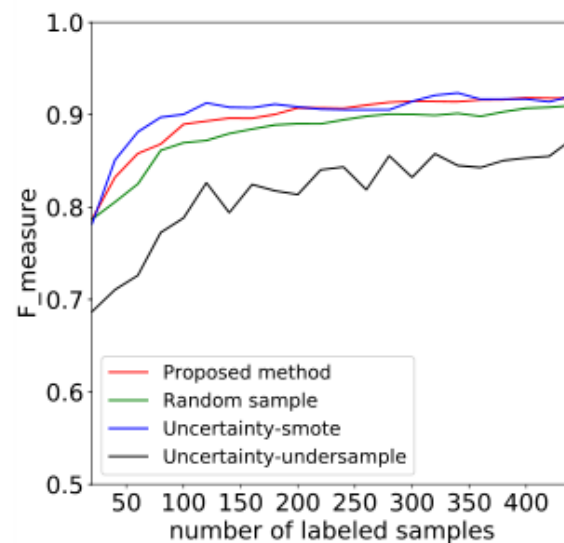
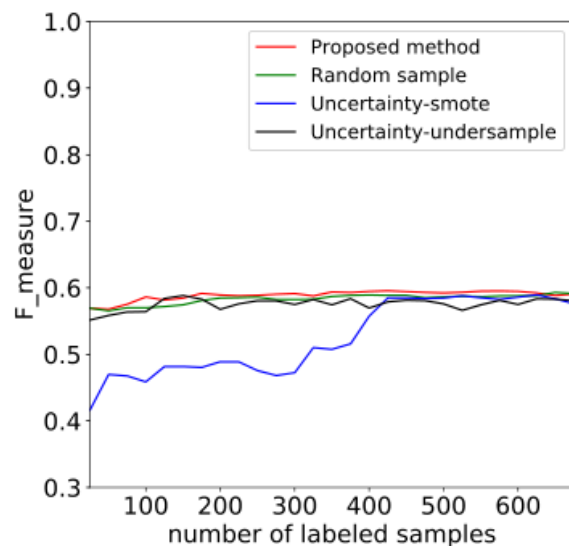
F_measure: suggested in [18], which mixes *recall* and *precision* as an average:

$$F_measure = \frac{2 \times Recall \times Precision}{Recall + Precision} \quad (7)$$

G_mean: When the performance of both classes is concerned, both *specificity* and *recall* are expected to be high in the meantime. It defined as :

$$G_mean = \sqrt{Specificity \times Recall} \quad (8)$$

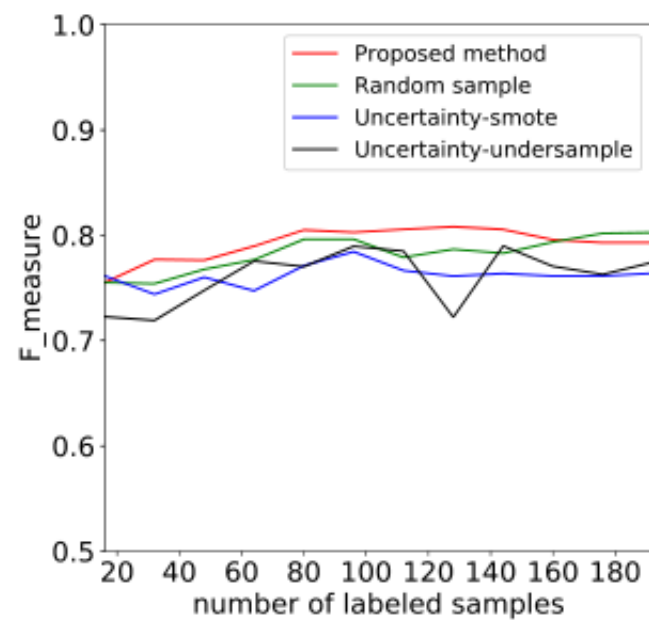
Experiments: Results



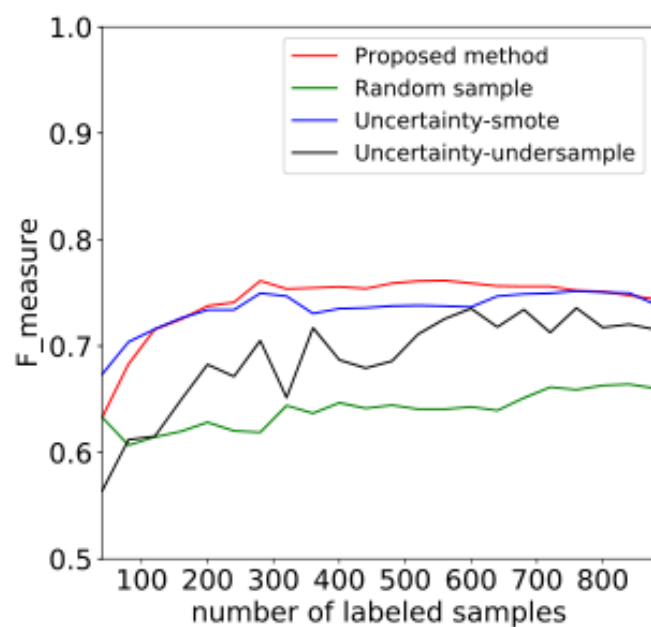
dataset Yeast1

Vehicle2

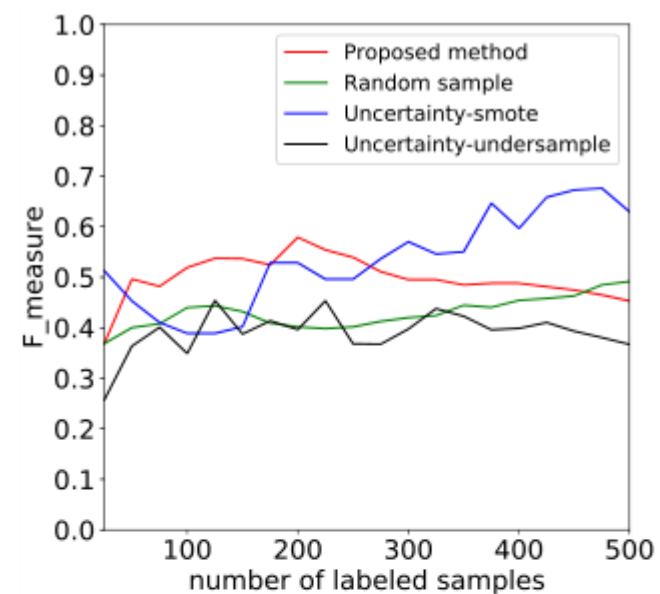
Segment0



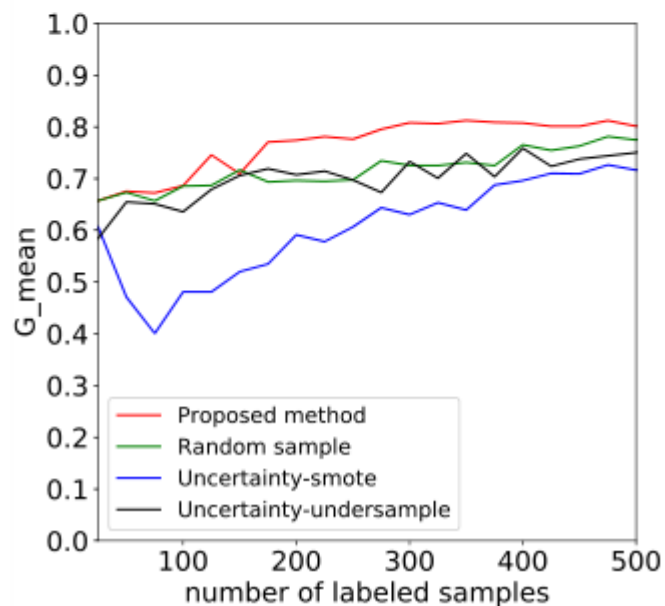
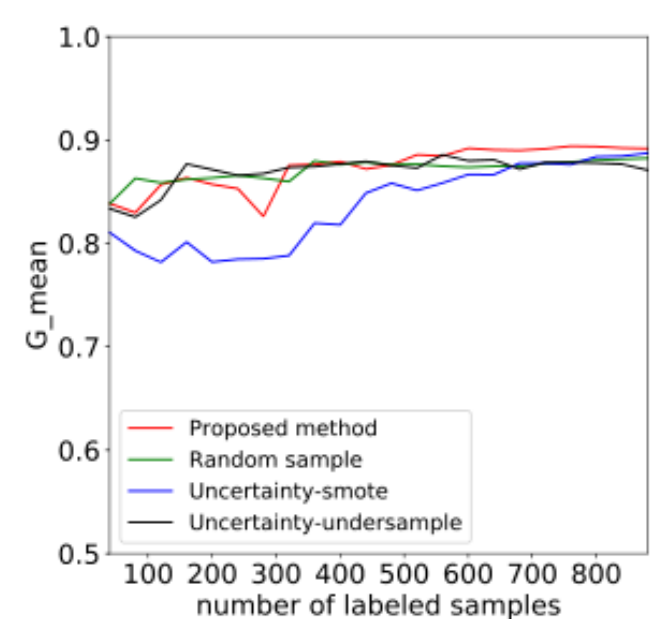
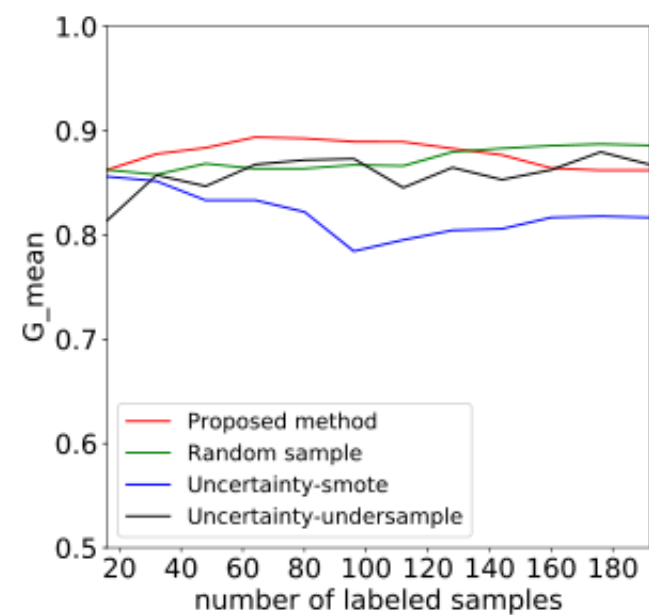
Ecoli1



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Abalone9-18



Thanks
