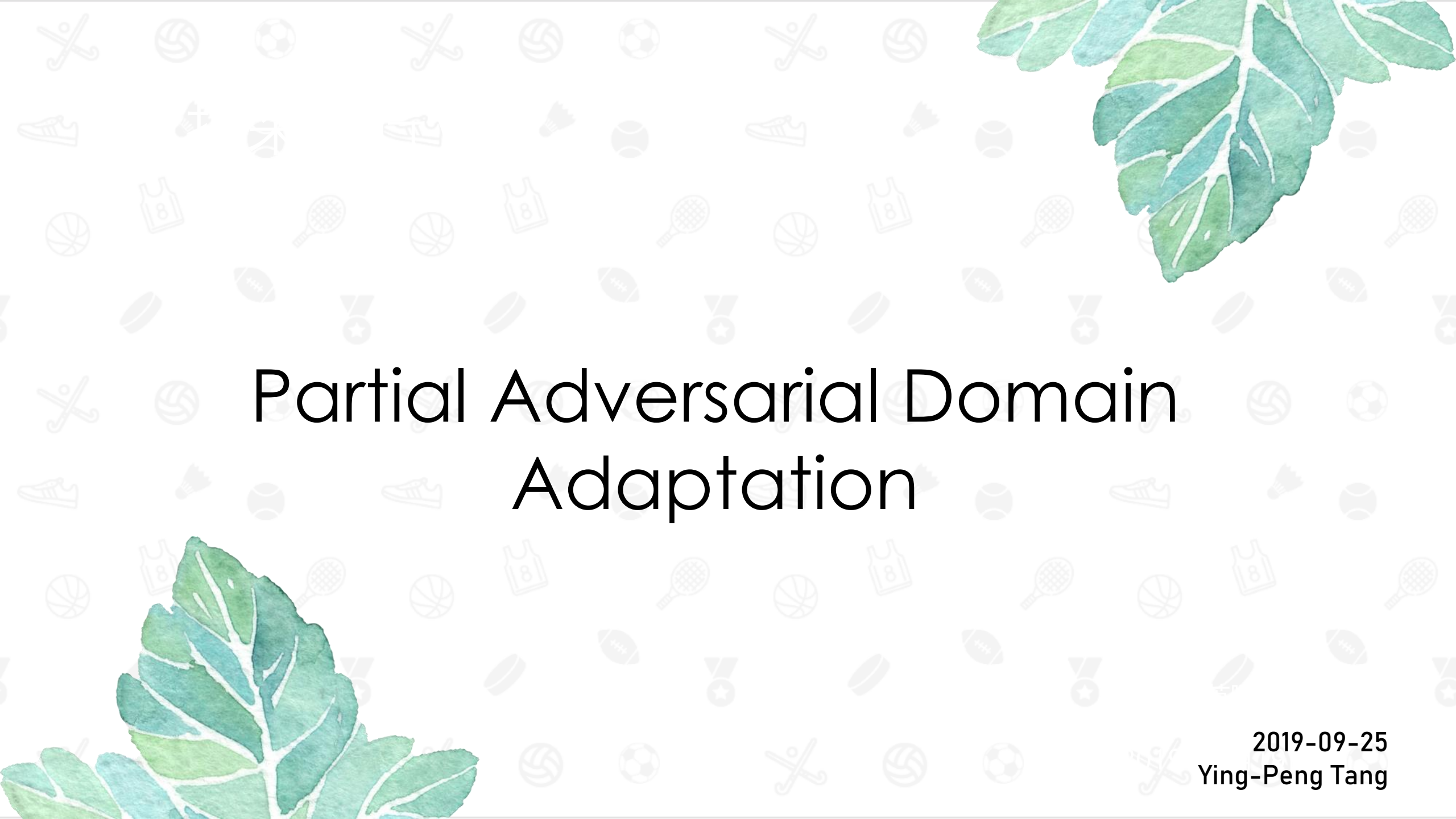


The background features a repeating pattern of various sports-related icons in a light gray color, including soccer balls, basketballs, tennis rackets, and medals. Two large, detailed green leaves are positioned in the top right and bottom left corners, adding a naturalistic touch to the design.

Partial Adversarial Domain Adaptation

2019-09-25
Ying-Peng Tang

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Домаин Адаптатион



Source domain

- A different but relevant domains
- Abundant training examples



digital SLR camera



low-cost camera, flash



Target domain

- Target task
- Limited or no training examples



amazon.com



consumer images

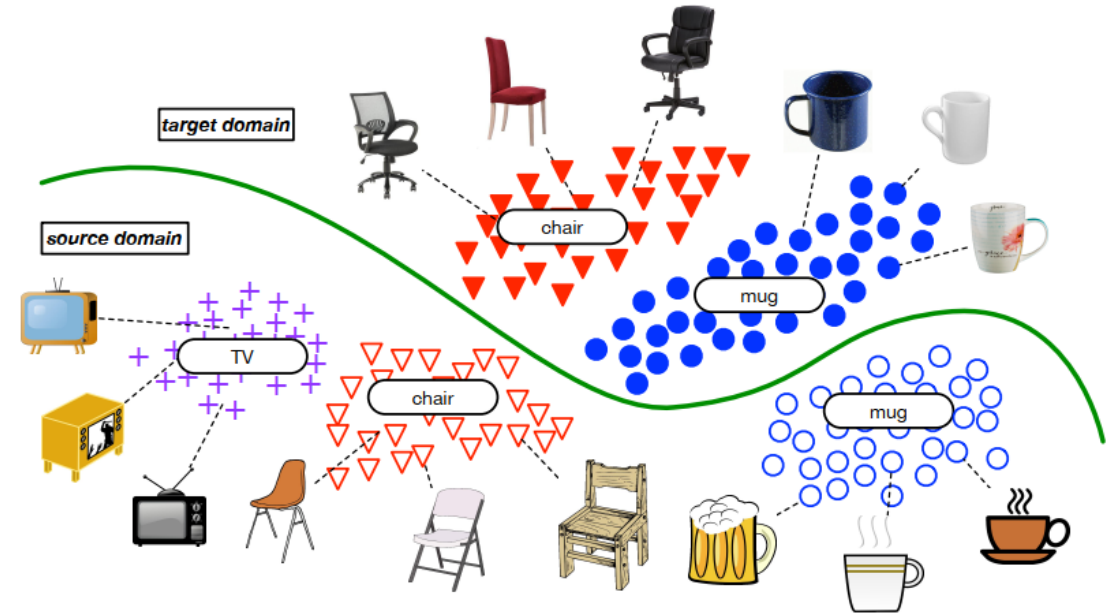


Партиал Домаин Адаптатион

Existing methods generally assume that the source and the target domains share identical label space.

A more practical scenario is that the target label space is a subspace of the source label space.

- Not always satisfied
- Cumbersome to seek for source domains for emerging target domains.





Адверсариал Домайн Адаптатион

$$= \frac{1}{n_s} \sum_{\mathbf{x}_i \in \mathcal{D}_s} L_y (G_y (G_f (\mathbf{x}_i)), y_i) - \frac{\lambda}{n_s + n_t} \sum_{\mathbf{x}_i \in \mathcal{D}_s \cup \mathcal{D}_t} L_d (G_d (G_f (\mathbf{x}_i)), d_i)$$

L: loss

G_f: Feature extractor

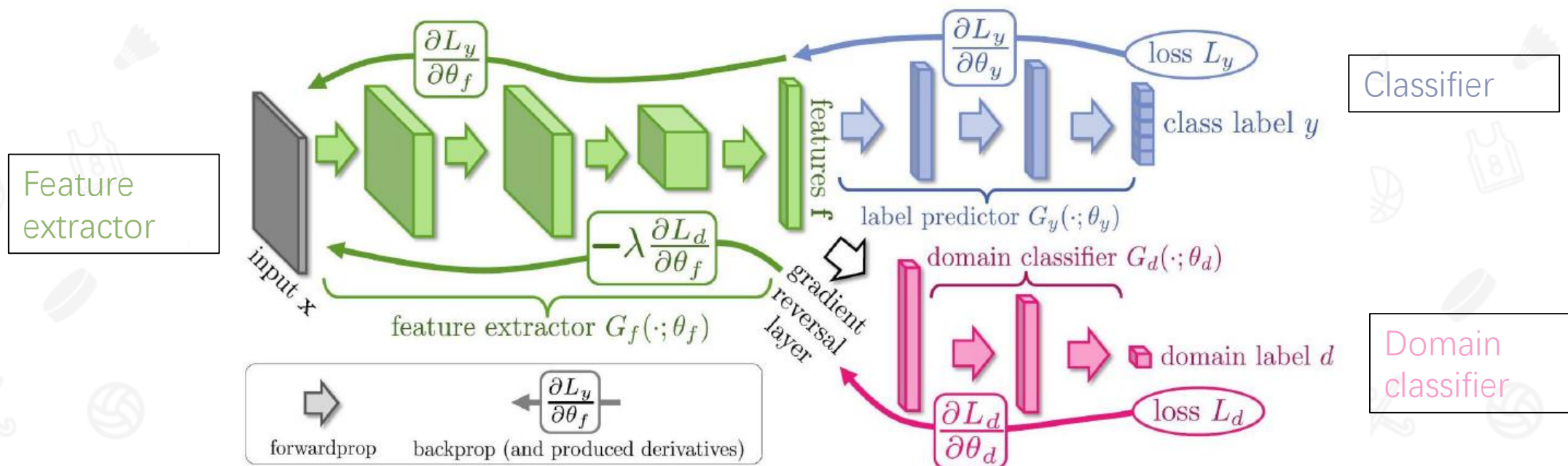
G_y: Classifier

G_d: Domain classifier

x, y: example, label

d: domain label (source 1, target 0)

n: number of examples





Партиал Домаин Адаптатион

PDA setting : $\mathcal{C}_t \subseteq \mathcal{C}_s$

Outlier label space : $\mathcal{C}_s \setminus \mathcal{C}_t$

Target label space : $\mathcal{C}_t$

- Aligning the whole source domain will cause negative transfer since the target domain is also forced to match the outlier label space
- The target domain is unsupervised. We do not know which class is the target class.

Key idea: re-weighting.

ECCV18



Partial Adversarial Domain Adaptation

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School of Software, Tsinghua University, China

National Engineering Laboratory for Big Data Software

Beijing National Research Center for Information Science and Technology



Метход

Key idea: class-level re-weighting. How to find the outlier classes?

Motivation: Since the source outlier label space and target label space are disjoint, **the target data should be significantly dissimilar to the source data** in the outlier label space

Method: Take the prediction of target data as the class-weight.

$$\gamma = \frac{1}{n_t} \sum_{i=1}^{n_t} \hat{y}_i$$

$$\begin{aligned} C(\theta_f, \theta_y, \theta_d) = & \frac{1}{n_s} \sum_{\mathbf{x}_i \in \mathcal{D}_s} \gamma_{y_i} L_y(G_y(G_f(\mathbf{x}_i)), y_i) \\ & - \frac{\lambda}{n_s} \sum_{\mathbf{x}_i \in \mathcal{D}_s} \gamma_{y_i} L_d(G_d(G_f(\mathbf{x}_i)), d_i) \\ & - \frac{\lambda}{n_t} \sum_{\mathbf{x}_i \in \mathcal{D}_t} L_d(G_d(G_f(\mathbf{x}_i)), d_i) \end{aligned}$$

CVPR18



Importance Weighted Adversarial Nets for Partial Domain Adaptation

Jing Zhang, Zewei Ding, Wanqing Li, Philip Ogunbona
Advanced Multimedia Research Lab, University of Wollongong, Australia



Метход

Key idea: image-level re-weighting

Source domain label: 1

Target domain label: 0

For source domain example:

if $D^*(z) \approx 1$ highly likely come from the outlier classes

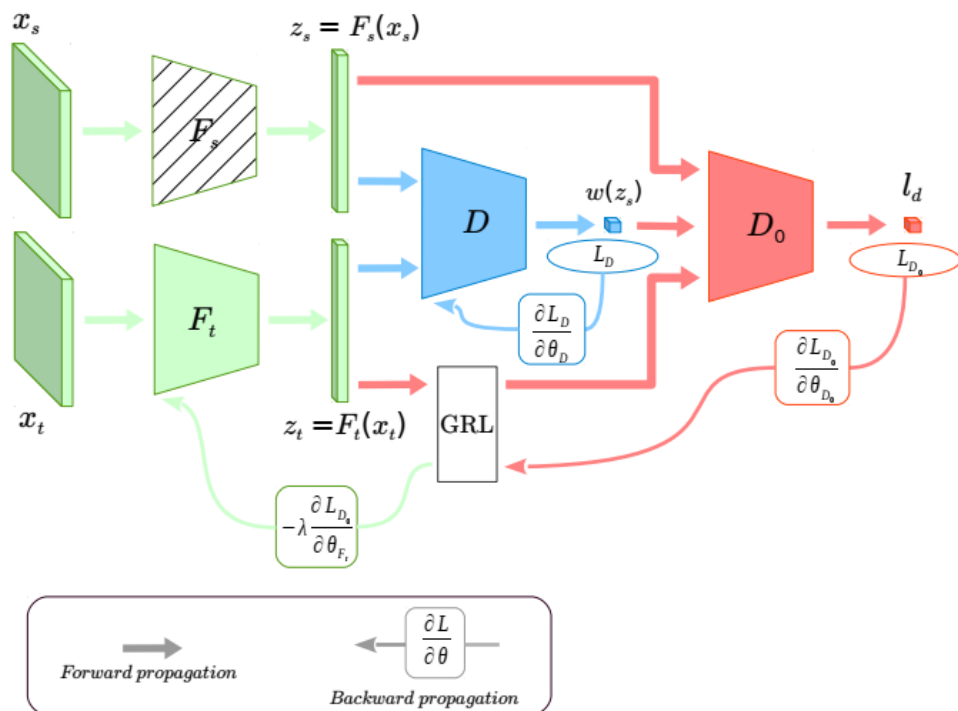
if $D^*(z) \approx 0$ more likely come from the shared classes

$$\tilde{w}(\mathbf{z}) = 1 - D^*(\mathbf{z}) = \frac{1}{\frac{p_s(\mathbf{z})}{p_t(\mathbf{z})} + 1}$$

$$w(\mathbf{z}) = \frac{\tilde{w}(\mathbf{z})}{\mathbb{E}_{\mathbf{z} \sim p_s(\mathbf{z})} \tilde{w}(\mathbf{z})}$$

Трицкс

- Adopt the unshared feature extractors for source and target domains
- Initialize F_t using the parameter of F_s
- Use an auxiliary domain classifier D for obtaining the $w(z)$
- Minimize the entropy of target domain data



$$\min_{F_s, C} \mathcal{L}_s(F_s, C) = -\mathbb{E}_{\mathbf{x}, y \sim p_s(\mathbf{x}, y)} \sum_{k=1}^K \mathbb{1}_{[k=y]} \log C(F_s(\mathbf{x}))$$

$$\min_D \mathcal{L}_D(D, F_s, F_t) = -(\mathbb{E}_{\mathbf{x} \sim p_s(\mathbf{x})} [\log D(F_s(\mathbf{x}))] + \mathbb{E}_{\mathbf{x} \sim p_t(\mathbf{x})} [\log(1 - D(F_t(\mathbf{x})))])$$

$$\min_{F_t} \max_{D_0} \mathcal{L}_w(C, D_0, F_s, F_t) =$$

$$\begin{aligned} & \gamma \mathbb{E}_{\mathbf{x} \sim p_t(\mathbf{x})} H(C(F_t(\mathbf{x}))) \\ & + \lambda (\mathbb{E}_{\mathbf{x} \sim p_s(\mathbf{x})} [w(\mathbf{z}) \log D_0(F_s(\mathbf{x}))] \\ & + \mathbb{E}_{\mathbf{x} \sim p_t(\mathbf{x})} [\log(1 - D_0(F_t(\mathbf{x})))] \end{aligned}$$

CVPR19



Learning to Transfer Examples for Partial Domain Adaptation

Zhangjie Cao^{1*}, Kaichao You^{1*}, Mingsheng Long¹(✉), Jianmin Wang¹, and Qiang Yang²

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²Hong Kong University of Science and Technology, China



Метход

Key idea: image-level re-weighting.

$$E_{G_y} = \frac{1}{n_s} \sum_{i=1}^{n_s} w(\mathbf{x}_i^s) L(G_y(G_f(\mathbf{x}_i^s), \mathbf{y}_i^s)) \\ + \frac{\gamma}{n_t} \sum_{j=1}^{n_t} H(G_y(G_f(\mathbf{x}_j^t))),$$

$$E_{G_d} = -\frac{1}{n_s} \sum_{i=1}^{n_s} w(\mathbf{x}_i^s) \log(G_d(G_f(\mathbf{x}_i^s))) \\ - \frac{1}{n_t} \sum_{j=1}^{n_t} \log(1 - G_d(G_f(\mathbf{x}_j^t))),$$



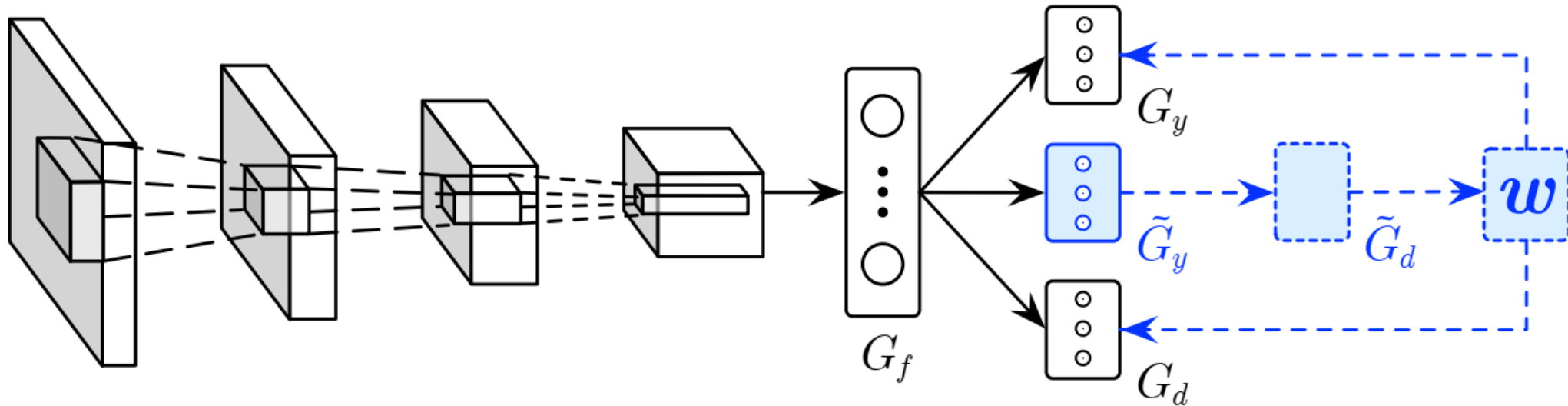
Хоч то гет $\psi(\mathbf{z})$

- Consider the domain information (transferability)

Use an auxiliary domain discriminator $\tilde{G}_d$

- Consider the discriminative information (relevance)

Use an auxiliary classifier $\tilde{G}_y$, Within $\tilde{G}_y$, the feature from feature extractor G_f are transformed to $|C_s|$ dimension $\mathbf{z}$, Then $\mathbf{z}$ will be passed through a leaky-softmax activation.





Хоч то гет ш(ш)

$$\tilde{G}_d(G_f(\mathbf{x}_i)) = \sum_{c=1}^{|\mathcal{C}_s|} \tilde{G}_y^c(G_f(\mathbf{x}_i)) \quad w(\mathbf{x}_i^s) = 1 - \tilde{G}_d(G_f(\mathbf{x}_i^s)).$$

$$E_{\tilde{G}_d} = -\frac{1}{n_s} \sum_{i=1}^{n_s} \log(\tilde{G}_d(G_f(\mathbf{x}_i^s))) \quad w(\mathbf{x}) \leftarrow \frac{w(\mathbf{x})}{\frac{1}{B} \sum_{i=1}^B w(\mathbf{x}_i)}$$
$$-\frac{1}{n_t} \sum_{j=1}^{n_t} \log(1 - \tilde{G}_d(G_f(\mathbf{x}_j^t)))$$

Motivation: As the auxiliary label predictor $\tilde{G}_y$ is trained on source examples and labels, the prediction for **source data should be certain**, for **target data should be uncertain**.

Therefore, the element-sum of the leaky-softmax outputs is closer to 1 for source examples and closer to 0 for target examples.



Объецииве фупцион

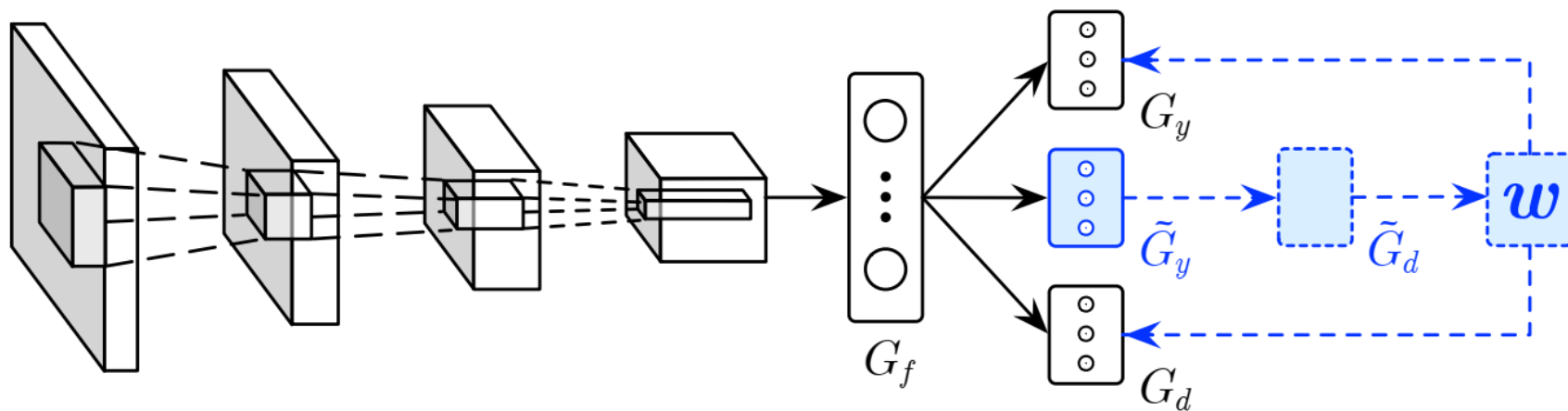
$$(\hat{\theta}_f, \hat{\theta}_y) = \arg \min_{\theta_f, \theta_y} E_{G_y} - E_{G_d}$$

$$(\hat{\theta}_d) = \arg \min_{\theta_d} E_{G_d},$$

$$(\hat{\theta}_{\tilde{y}}) = \arg \min_{\theta_{\tilde{y}}} E_{\tilde{G}_y} + E_{\tilde{G}_d}.$$

$$E_{G_y} = \frac{1}{n_s} \sum_{i=1}^{n_s} w(\mathbf{x}_i^s) L(G_y(G_f(\mathbf{x}_i^s), \mathbf{y}_i^s)) \\ + \frac{\gamma}{n_t} \sum_{j=1}^{n_t} H(G_y(G_f(\mathbf{x}_j^t))),$$

$$E_{G_d} = -\frac{1}{n_s} \sum_{i=1}^{n_s} w(\mathbf{x}_i^s) \log(G_d(G_f(\mathbf{x}_i^s))) \\ - \frac{1}{n_t} \sum_{j=1}^{n_t} \log(1 - G_d(G_f(\mathbf{x}_j^t))),$$





Ешперимент

Dataset

- **Office-31**, 31 categories in total, 3 Domain. 31 categories for the source domain and 10 categories for the target domain. $A \rightarrow W$, $D \rightarrow W$, $W \rightarrow D$, $A \rightarrow D$, $D \rightarrow A$ and $W \rightarrow A$
- **Office-Home**, 65 categories, 4 domains: **Ar**, **Cl**, **Pr**, **Rw**. first 25 categories in alphabetical order as the target domain and images from all 65 categories as the source domain
- **ImageNet(1000) $\rightarrow$ Caltech (84)** They share 84 classes
- **Caltech (256) $\rightarrow$ ImageNet (84)** They share 84 classes

Compared methods

- ResNet
- Deep Adaptation Network (**DAN**)
- Domain-Adversarial Neural Networks (**DANN**)
- Adversarial Discriminative Domain Adaptation (**ADDA**)
- Residual Transfer Networks (**RTN**)
- Selective Adversarial Network (**SAN**)
- Importance Weighted Adversarial Network (**IWAN**)
- Partial Adversarial Domain Adaptation (**PADA**)

Table 1. Classification Accuracy (%) for Partial Domain Adaptation on Office-Home Dataset (**ResNet**)

Method	Office-Home												
	Ar→Cl	Ar→Pr	Ar→Rw	Cl→Ar	Cl→Pr	Cl→Rw	Pr→Ar	Pr→Cl	Pr→Rw	Rw→Ar	Rw→Cl	Rw→Pr	Avg
ResNet [15]	46.33	67.51	75.87	59.14	59.94	62.73	58.22	41.79	74.88	67.40	48.18	74.17	61.35
DANN [10]	43.76	67.90	77.47	63.73	58.99	67.59	56.84	37.07	76.37	69.15	44.30	77.48	61.72
ADDA [37]	45.23	68.79	79.21	64.56	60.01	68.29	57.56	38.89	77.45	70.28	45.23	78.32	62.82
RTN [22]	49.31	57.70	80.07	63.54	63.47	73.38	65.11	41.73	75.32	63.18	43.57	80.50	63.07
IWAN [43]	53.94	54.45	78.12	61.31	47.95	63.32	54.17	52.02	81.28	76.46	56.75	82.90	63.56
SAN [5]	44.42	68.68	74.60	67.49	64.99	77.80	59.78	44.72	80.07	72.18	50.21	78.66	65.30
PADA [6]	51.95	67.00	78.74	52.16	53.78	59.03	52.61	43.22	78.79	73.73	56.60	77.09	62.06
ETN	59.24	77.03	79.54	62.92	65.73	75.01	68.29	55.37	84.37	75.72	57.66	84.54	70.45

Table 2. Classification Accuracy (%) for Partial Domain Adaptation on Office-31 and ImageNet-Caltech (**ResNet**)

Method	Office-31							ImageNet-Caltech		Avg
	A→W	D→W	W→D	A→D	D→A	W→A	Avg	I → C	C → I	
ResNet [15]	75.59±1.09	96.27±0.85	98.09±0.74	83.44±1.12	83.92±0.95	84.97±0.86	87.05±0.94	69.69±0.78	71.29±0.74	70.49±0.76
DAN [21]	59.32±0.49	73.90±0.38	90.45±0.36	61.78±0.56	74.95±0.67	67.64±0.29	71.34±0.46	71.30±0.46	60.13±0.50	65.72±0.48
DANN [10]	73.56±0.15	96.27±0.26	98.73±0.20	81.53±0.23	82.78±0.18	86.12±0.15	86.50±0.20	70.80±0.66	67.71±0.76	69.23±0.71
ADDA [37]	75.67±0.17	95.38±0.23	99.85±0.12	83.41±0.17	83.62±0.14	84.25±0.13	87.03±0.16	71.82±0.45	69.32±0.41	70.57±0.43
RTN [22]	78.98±0.55	93.22±0.52	85.35±0.47	77.07±0.49	89.25±0.39	89.46±0.37	85.56±0.47	75.50±0.29	66.21±0.31	70.85±0.30
IWAN [43]	89.15±0.37	99.32±0.32	99.36±0.24	90.45±0.36	95.62±0.29	94.26±0.25	94.69±0.31	78.06±0.40	73.33±0.46	75.70±0.43
SAN [5]	93.90±0.45	99.32±0.52	99.36±0.12	94.27±0.28	94.15±0.36	88.73±0.44	94.96±0.36	77.75±0.36	75.26±0.42	76.51±0.39
PADA [6]	86.54±0.31	99.32±0.45	100.00±0.00	82.17±0.37	92.69±0.29	95.41±0.33	92.69±0.29	75.03±0.36	70.48±0.44	72.76±0.40
ETN	94.52±0.20	100.00±0.00	100.00±0.00	95.03±0.22	96.21±0.27	94.64±0.24	96.73±0.16	83.23±0.24	74.93±0.28	79.08±0.26

Ешперимент

Table 3. Classification Accuracy (%) of ETN and its variants for Partial Domain Adaptation on Office-Home Dataset (**ResNet**)

Method	Office-Home												
	Ar→Cl	Ar→Pr	Ar→Rw	Cl→Ar	Cl→Pr	Cl→Rw	Pr→Ar	Pr→Cl	Pr→Rw	Rw→Ar	Rw→Cl	Rw→Pr	Avg
ETN w/o classifier	56.18	71.93	79.32	65.11	65.57	73.66	65.47	52.90	82.88	72.93	56.93	82.91	68.93
ETN w/o auxiliary	48.36	50.42	79.13	56.57	45.88	65.49	56.38	49.07	77.53	75.57	58.81	78.32	61.79
ETN	59.24	77.03	79.54	62.92	65.73	75.01	68.29	55.37	84.37	75.72	57.66	84.54	70.45

w/o classifier: without weights on the

source classifier Table 4. Classification Accuracy (%) for Partial Domain Adaptation on Office-31 (**VGG**)

Method	Office-31						
	A→W	D→W	W→D	A→D	D→A	W→A	Avg
VGG [34]	60.34±0.84	97.97±0.63	99.36±0.36	76.43±0.48	72.96±0.56	79.12±0.54	81.03± 0.57
DAN [21]	58.78±0.43	85.86±0.32	92.78±0.28	54.76±0.44	55.42±0.56	67.29±0.20	69.15±0.37
DANN [10]	50.85±0.12	95.23±0.24	94.27±0.16	57.96±0.20	51.77±0.14	62.32±0.12	68.73±0.16
ADDA [37]	53.28±0.15	94.33±0.18	95.36±0.08	58.78±0.12	50.24±0.10	63.34±0.08	69.22±0.12
RTN [22]	69.35±0.42	98.42±0.48	99.59±0.32	75.43±0.38	81.45±0.32	82.98±0.36	84.54±0.38
IWAN [43]	82.90±0.31	79.75±0.26	88.53±0.16	90.95±0.33	89.57±0.24	93.36±0.22	87.51±0.25
SAN [5]	83.39±0.36	99.32±0.45	100.00±0.00	90.70±0.20	87.16±0.23	91.85±0.35	92.07±0.27
PADA [6]	86.05±0.36	99.42±0.24	100.00±0.00	81.73±0.34	93.00±0.24	95.26±0.27	92.54±0.24
ETN	85.66±0.16	100.00±0.00	100.00±0.00	89.43±0.17	95.93±0.23	92.28±0.20	96.74±0.13

Ешперимент

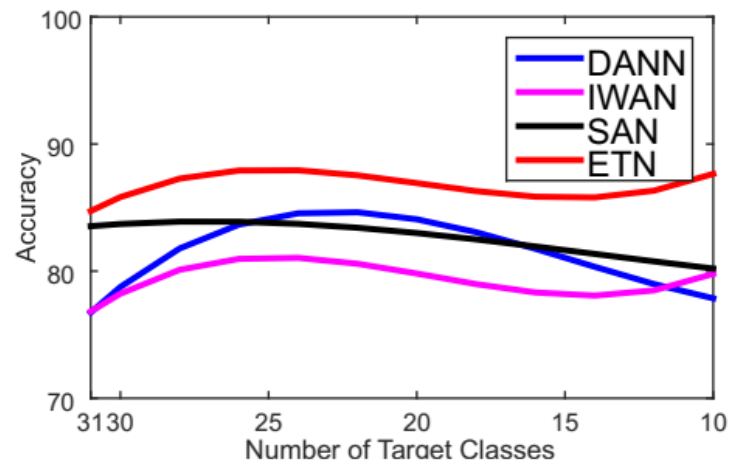


Figure 4. Accuracy by varying #target classes.

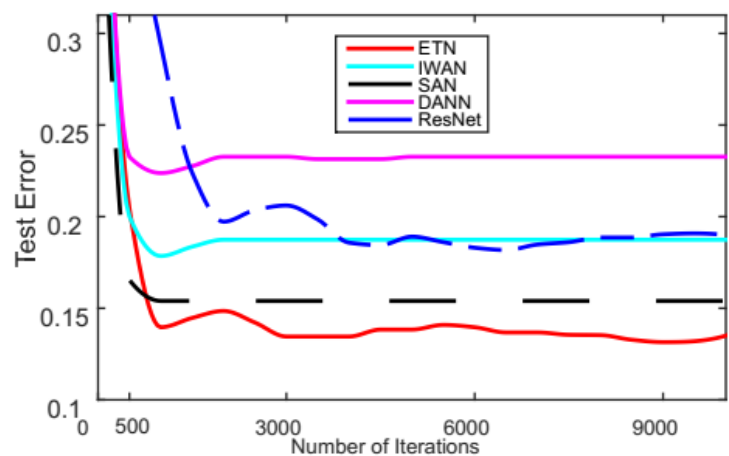
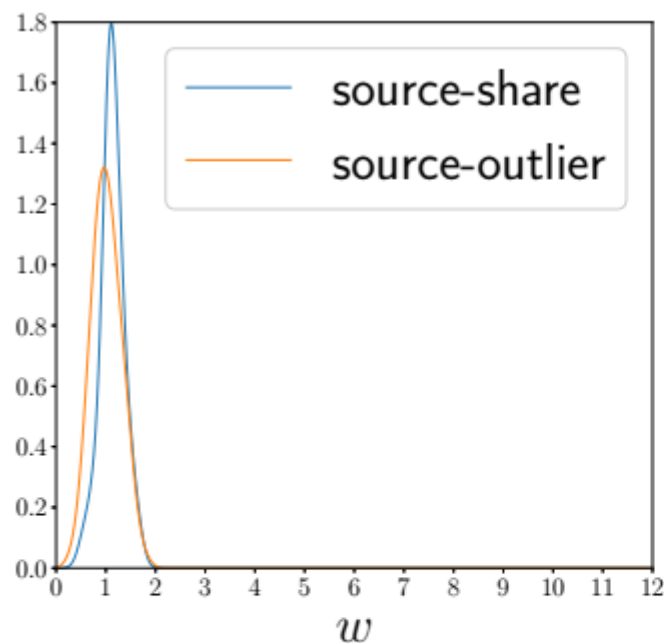
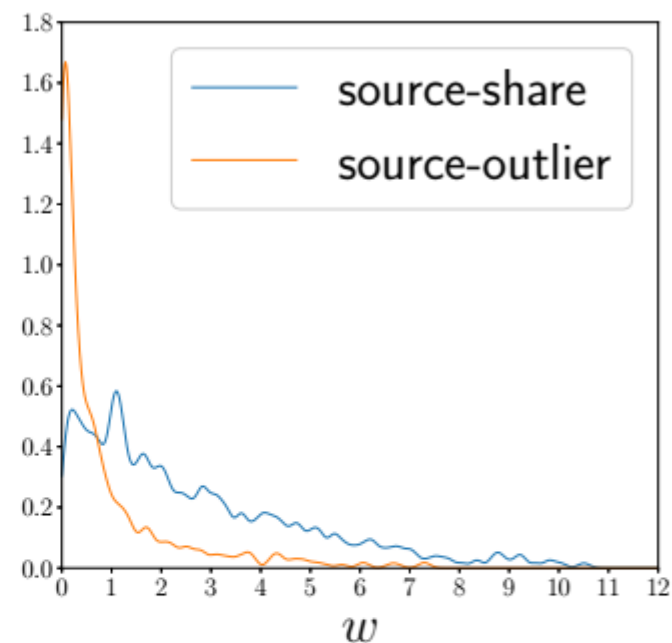


Figure 5. Target test error w.r.t. to #iterations.



(a) IWAN



(b) ETN

Figure 6. Density function of the importance weights of source examples in the shared label space $\mathcal{C}_t$ and outlier label space $\mathcal{C}_s \setminus \mathcal{C}_t$ for IWAN and ETN.